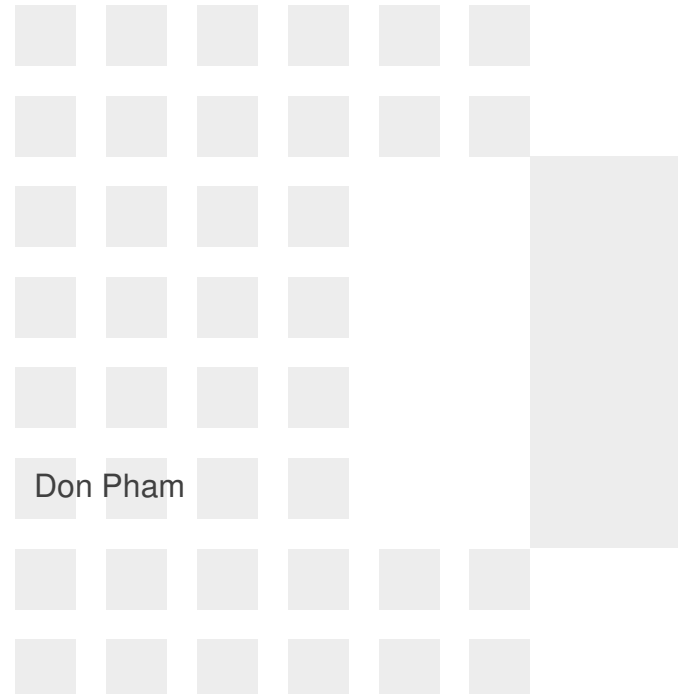




Think Automation and beyond...

CONFIDENTIAL

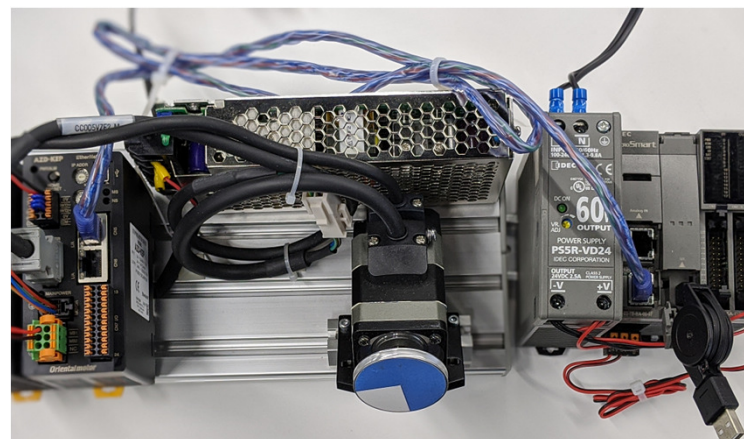
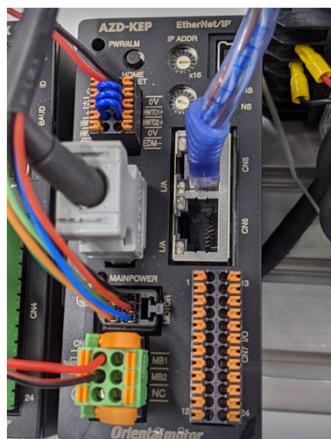
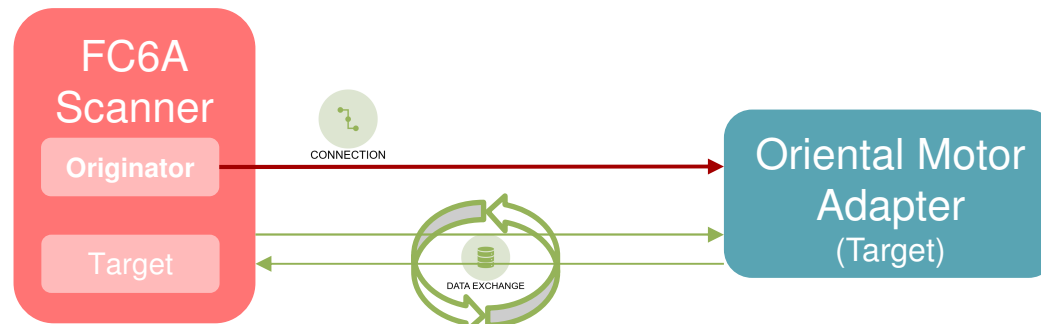
FC6A Plus EtherNet/IP™



EtherNet/IP™

Example 1: FC6A and Oriental Motor motor driver

- Oriental Motor AZD-KEP motor driver is an Adapter
- FC6A Plus will be configured as a Scanner with Originator function



Adapter parameters (required for communication)

- In order to configure the FC6A Plus to communicate with the Adapter, we need to find out some Adapter's parameters
- There are two methods of finding this information
 1. Adapter's device user manual

Electronic Key: Vendor ID, Device Type

Communications standards	EtherNet/IP (conforms to CT16)	
Vendor ID	187: Oriental Motor Company	
Device type	43: Generic Device	
Transmission rate	10/100 Mb	
Communication mode	Full duplex	
Cable specifications	Shielded twisted pair	
Number of occupied bytes	Output (scanner → driver)	40 bytes
	Input (driver → scanner)	56 bytes
Implicit	Number of connections	2
	Connection type	Exclusive connection
	Communication cycle (RPI)	1 to 3,200 ms

Input data format

Contents of the Input data is as follows. The order of data is in little-endian format.

Assembly Instance	Attribute	Byte	Size (byte)	Description
100	3	0, 1	2	Remote I/O (R-IN)
		2, 3	2	Operation data number selection
		4, 5	2	Fixed I/O (IN)
101	3	6, 7	2	Direct data operation operation type
		8 to 11	4	Direct data operation position
		12 to 15	4	Direct data operation operating speed
		16 to 19	4	Direct data operation starting/changing rate
		20 to 23	4	Direct data operation stopping deceleration
		24, 25	2	Direct data operation operating current
		26, 27	2	Direct data operation forwarding destination

Output data format

Descriptions of the Output data are as follows. The order of data is in little-endian format.

Assembly Instance	Attribute	Byte	Size (byte)	Description
101	3	0, 1	2	Remote I/O (R-IN)
		2, 3	2	Operation data number selection
		4, 5	2	Fixed I/O (IN)
		6, 7	2	Direct data operation operation type
		8 to 11	4	Direct data operation position
		12 to 15	4	Direct data operation operating speed
		16 to 19	4	Direct data operation starting/changing rate
20 to 23	4	Direct data operation stopping deceleration		
101	3	24, 25	2	Direct data operation operating current
		26, 27	2	Direct data operation forwarding destination

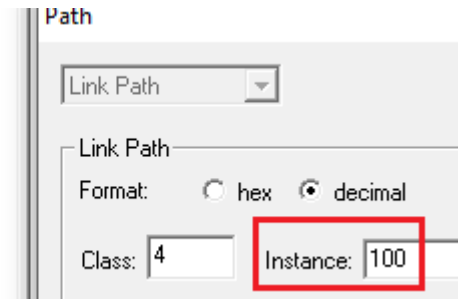
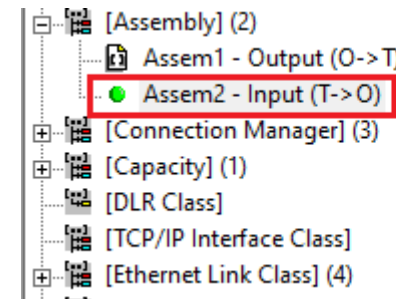
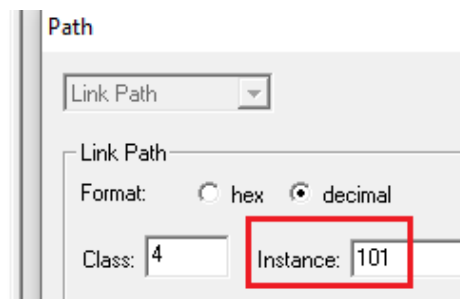
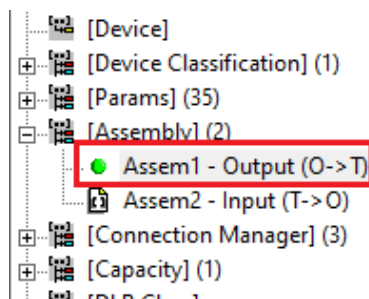
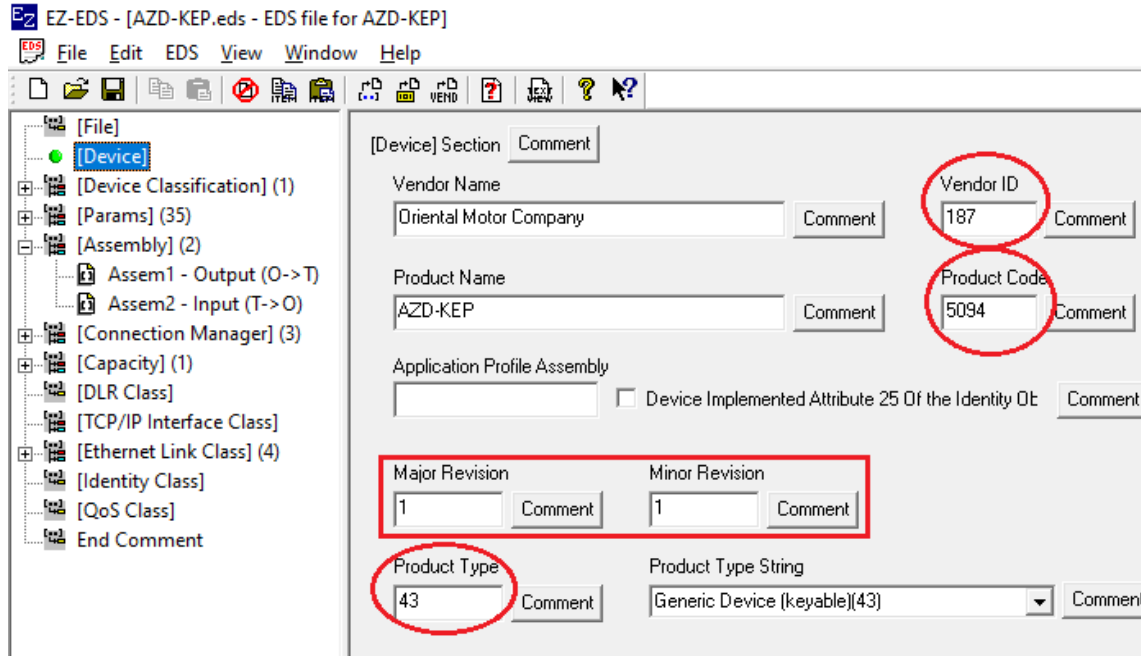
Adapter parameters (required for communication)

■ There are two methods of finding this information

2. Electronic Data Sheet (EDS) File

- Most EtherNet/IP Adapters provide an EDS file, so users don't have to manually look up and enter this information in the Scanner settings
- However, WindLDR currently does not support EDS file import
- EDS file import will be supported in later WindLDR version
- For now, users can use the free EDS extractor tool to extract
- EDS extractor tool
 - <https://www.odva.org/subscriptions-services/software/ez-eds-download/>

EDS extractor tool



Example 1: FC6A and Oriental Motor motor driver

- Step 1: Click Ethernet Port 2
- Step 2: Check EtherNet/IP Settings and click Configure

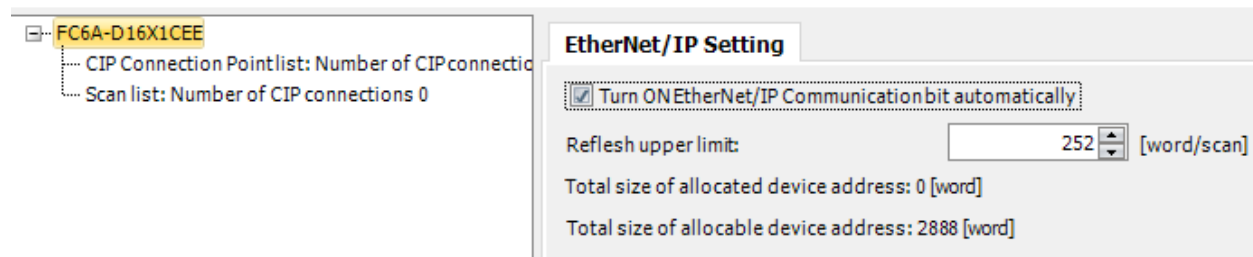
EtherNet/IP Settings

Enable EtherNet/IP

Configure

- Check the *Turn ON EtherNet/IP...box* if you want the FC6A to automatically enable EtherNet/IP communication

EtherNet/IP setting



FC6A-D16X1CEE

- ... CIP Connection Pointlist: Number of CIP connections 0
- ... Scan list: Number of CIP connections 0

EtherNet/IP Setting

Turn ON EtherNet/IP Communication bit automatically

Refresh upper limit: 252 [word/scan]

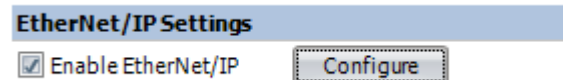
Total size of allocated device address: 0 [word]

Total size of allocable device address: 2888 [word]

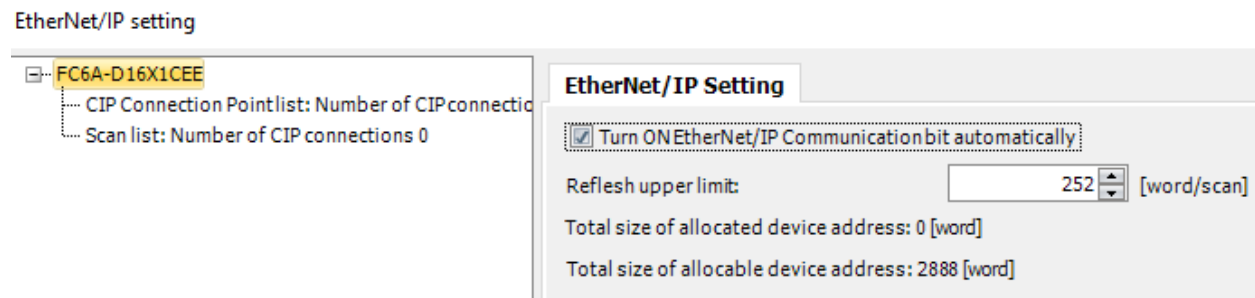
- **M8460: EtherNet/IP Communication Bit**
This special internal relay permits or prohibits EtherNet/IP communication.
OFF: Prohibit EtherNet/IP communication
ON: Permit EtherNet/IP communication

Example 1: FC6A and Oriental Motor motor driver

- Step 1: Click Ethernet Port 2
- Step 2: Check EtherNet/IP Settings and click Configure



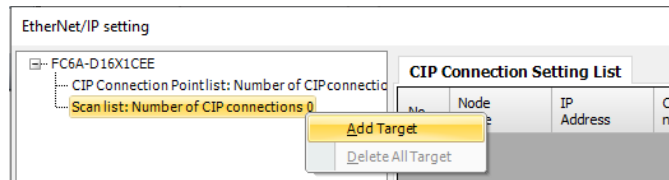
- Check the *Turn ON EtherNet/IP...box* if you want the FC6A to automatically enable EtherNet/IP communication



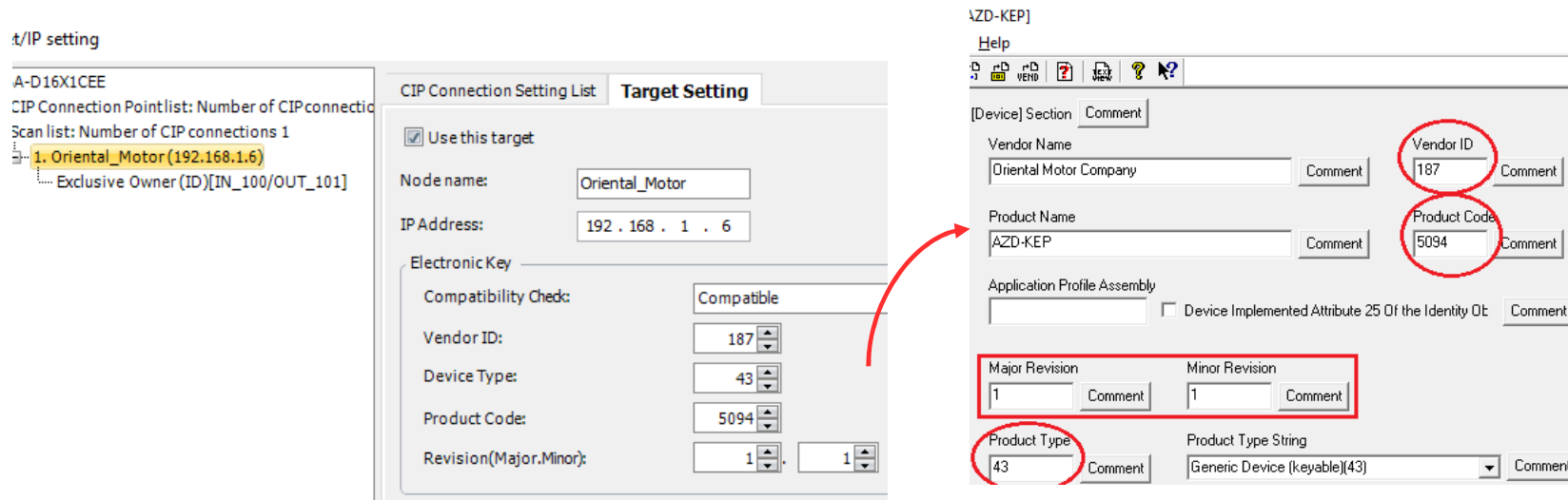
- **M8460: EtherNet/IP Communication Bit**
This special internal relay permits or prohibits EtherNet/IP communication.
OFF: Prohibit EtherNet/IP communication
ON: Permit EtherNet/IP communication

Example 1: FC6A and Oriental Motor motor driver

- Step 3: Right mouse click Scan list.. → Add Target

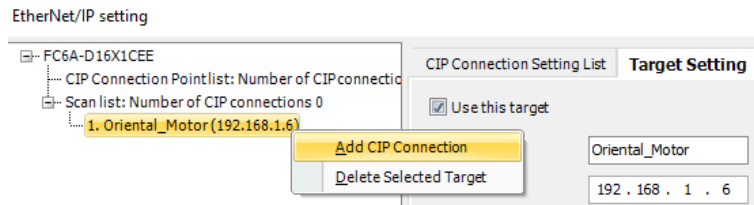


- Step 4: Under Target Setting tab, enter the Node name, IP Address and Electronic Key of the motor



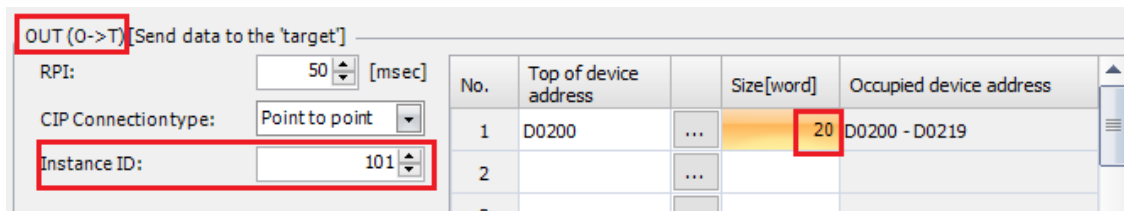
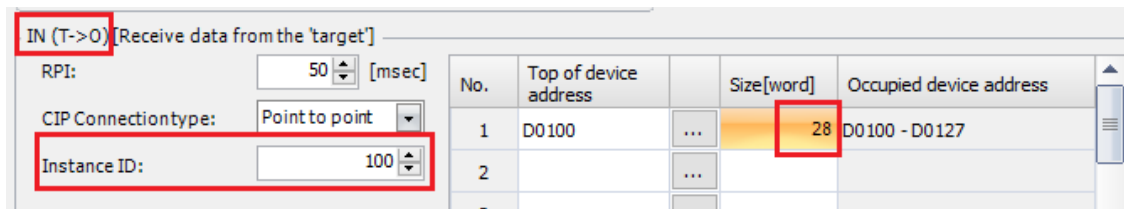
Example 1: FC6A and Oriental Motor motor driver

■ Step 5: Right mouse click and select Add CIP Connection



■ Step 6: In the CIP Connection Settings, fill in the Adapter parameters

- IN Instance ID = 100, Size = 28 Words
- OUT Instance ID = 101, Size = 20 Words



Adapter Settings

The screenshot displays the configuration interface for EtherNet/IP adapter settings. It is divided into two main sections for different assemblies.

Top Section (Assembly 2):

- Assembly:** Assem2 - Input (T->O)
- Link Path:** Oriental_Motor
- Exclusive Owner (ID):** RPI x 16
- Instance ID:** 100
- IN (T->O) [Receive data from the 'target']:**
 - RPI: 50 [msec]
 - CIP Connectiontype: Point to point
 - Instance ID: 100
 - | No. | Top of device address | Size[word] | Occupied device address |
|-----|-----------------------|------------|-------------------------|
| 1 | D0100 | 28 | D0100 - D0127 |
| 2 | | | |
| 3 | | | |
| 4 | | | |
 - Total data size: 28 [word] Remaining data size: 692 [word]
- OUT (O->T) [Send data to the 'target']:**
 - RPI: 50 [msec]
 - CIP Connectiontype: Point to point
 - Instance ID: 101
 - | No. | Top of device address | Size[word] | Occupied device address |
|-----|-----------------------|------------|-------------------------|
| 1 | D0200 | 20 | D0200 - D0219 |
| 2 | | | |
| 3 | | | |
| 4 | | | |
 - Total data size: 20 [word]

Bottom Section (Assembly 1):

- Assembly:** Assem1 - Output (O->T)
- Link Path:** Oriental_Motor
- Exclusive Owner (ID):** RPI x 16
- Instance ID:** 101
- IN (T->O) [Receive data from the 'target']:**
 - RPI: 50 [msec]
 - CIP Connectiontype: Point to point
 - Instance ID: 100
 - | No. | Top of device address | Size[word] | Occupied device address |
|-----|-----------------------|------------|-------------------------|
| 1 | D0100 | 28 | D0100 - D0127 |
| 2 | | | |
| 3 | | | |
| 4 | | | |
 - Total data size: 28 [word] Remaining data size: 692 [word]
- OUT (O->T) [Send data to the 'target']:**
 - RPI: 50 [msec]
 - CIP Connectiontype: Point to point
 - Instance ID: 101
 - | No. | Top of device address | Size[word] | Occupied device address |
|-----|-----------------------|------------|-------------------------|
| 1 | D0200 | 20 | D0200 - D0219 |
| 2 | | | |
| 3 | | | |
| 4 | | | |
 - Total data size: 20 [word]

Additional details on the right side of the interface include:

- Attribute directly addressable from the network:** 20 04 24 64 30 03
- Size of the Data Block (in bytes):** <None>
- NOTE:** Actual Size of the Data Block: Bits: 448 Bytes: 56 Words: 28

Red arrows in the image point from the 'Words' values in the notes to the 'Size[word]' column in the tables, and from the 'Instance ID' fields to the 'Instance ID' input boxes.

Example 1: FC6A and Oriental Motor motor driver

■ Step 7: Configure the rest of the settings

CIP Connection name

See pg 440 Manual for more details

Timeout

Sets the timeout

Configuration Instance ID

Some vendors use this parameter, and some don't

RPI

Requested package interval 10 to 10,000ms

CIP Connection type

Point-to-Point-receives data from target on a one-to-one basis

Multicast-multiple originators receive data from one target

Trigger of send

Cyclic-transmit data at the set RPI
COS-transmit data at the set RPI or when a value changes

Control Register

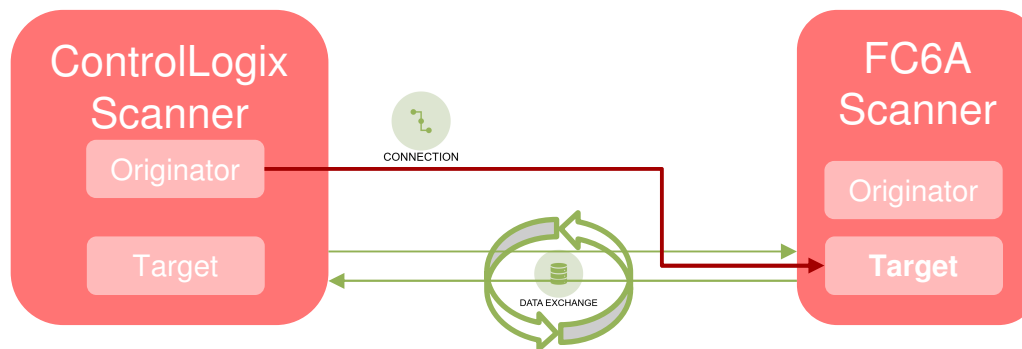
Sets the data registers that will be used by the CIP connection
 See pg 441 Manual

Top of the device address

Users define data registers in the FC6A

Example 2: FC6A and AB ControlLogix5555

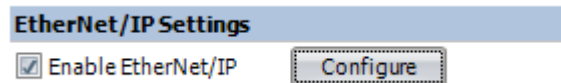
- AB ControlLogix is a Scanner with Originator function
- FC6A Plus will be configured as a Scanner with **Target** function



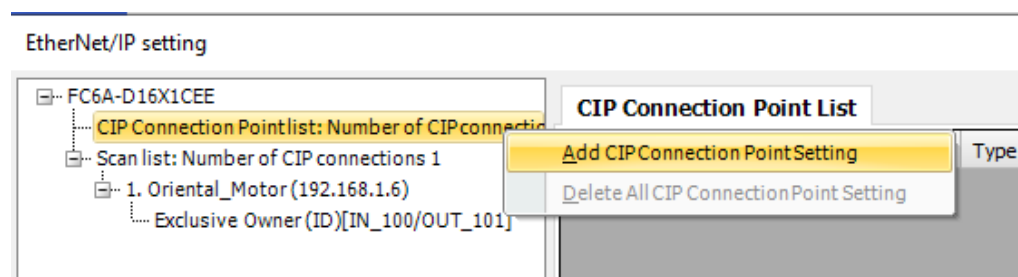
Example 2: FC6A and AB ControlLogix5555

■ WindLDR Configuration

- Step 1: Click Ethernet Port 2
- Step 2: Check EtherNet/IP Settings and click Configure



- Step 3: Right mouse click CIP Connection... → Add CIP Connection Point Setting



Example 2: FC6A and AB ControlLogix5555

■ WindLDR Configuration

- Step 4: FC6A sends values in D0-D1 to ControlLogix
 - Instance ID = 100 (Default. Can be set with other value)
 - CIP Tag: Optional
 - Type: IN (T → O)
 - Top of device address: D0, Size 2

CIP Connection Point Setting

Instance ID: Available Instance ID (100 to 197, 240 to 255 and 768 to 1279)

CIP Tag:

Type: Send data to the 'Originator'.

Device Allocation:

No.	Top of device address		Size[word]	Occupied device address
1	D0000	...	2	D0000 - D0001
2		...		

- Step 5: Repeat step 3 to add another connection point

Example 2: FC6A and AB ControlLogix5555

■ WindLDR Configuration

- Step 6: FC6A receives data from ControlLogix and stores in D400-D409
 - Instance ID = 101 (Needs to be different from other connection point)
 - CIP Tag: Optional
 - Type: OUT (O → T)

● **CIP Connection Point Setting**

Instance ID: Available Instance ID (100 to 197, 240 to 255 and 768 to 1279)

CIP Tag:

Type: **OUT (O->T)** Receive data from the 'Originator'.

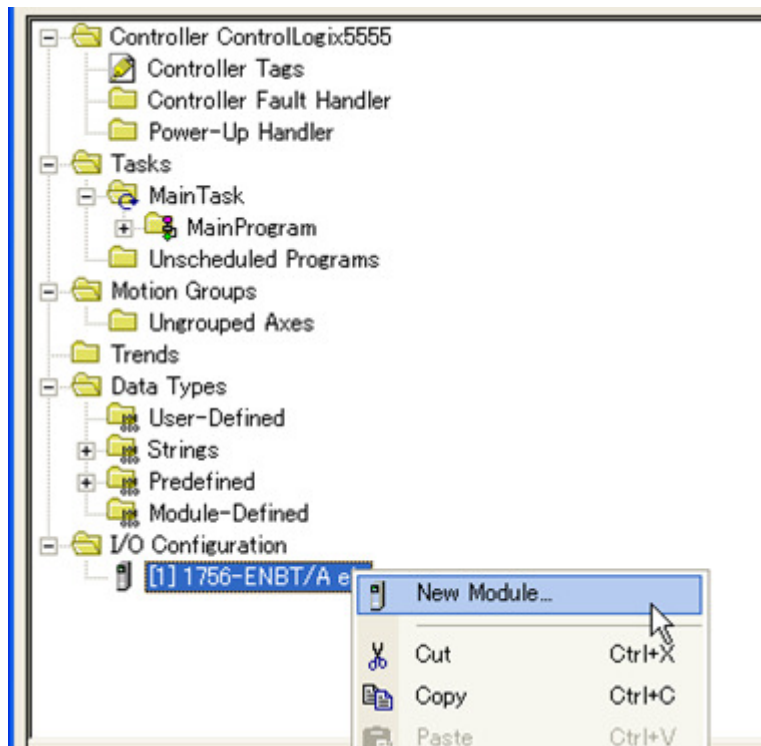
Device Allocation:

No.	Top of device address		Size[word]	Occupied device address
1	D0400	...	10	D0400 - D0409
2		...		

Example 2: FC6A and AB ControlLogix5555

■ RSLogix5000 Configuration

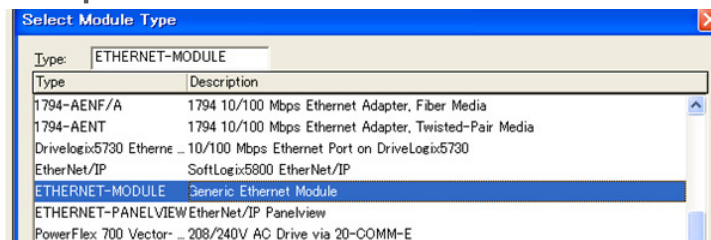
- Step 1: Select “1756-ENBT/A eip”
- Step 2: Select “Add New Module” from context menu



Example 2: FC6A and AB ControlLogix5555

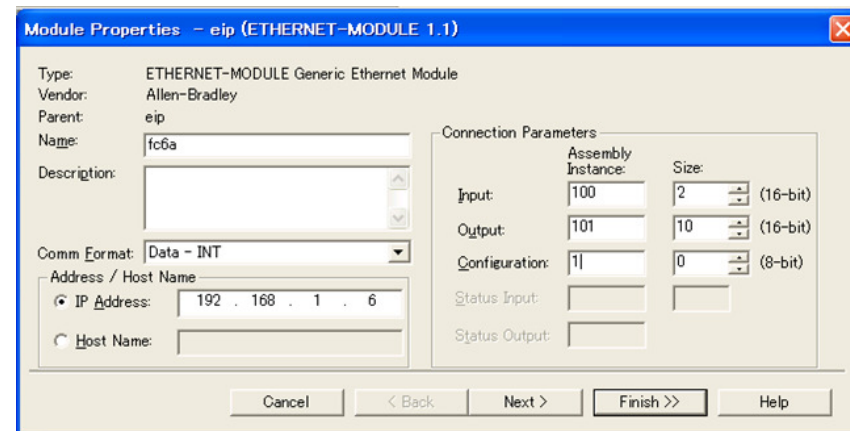
■ RSLogix5000 Configuration

- Step 3: Select “Generic Ethernet Module” from module list



- Step 4: Configure properties of FC6A Plus

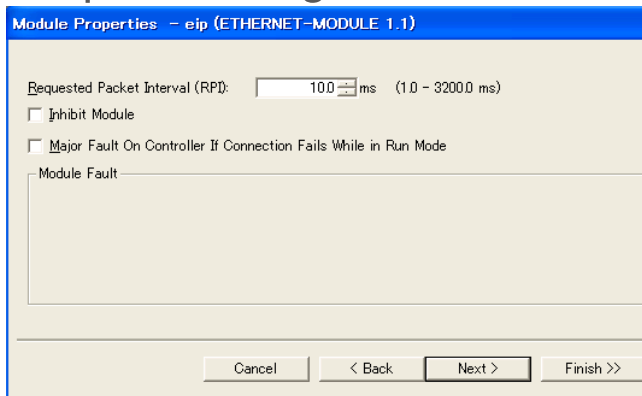
Name	Any name
IP Address	FC6A PLUS IP Address
Input (T → O)	Assembly Instance = 100 Size = 2
Output (O → T)	Assembly Instance = 101 Size = 10
Configuration	Assembly Instance = 1 Size = 0



Example 2: FC6A and AB ControlLogix5555

■ RSLogix5000 Configuration

- Step 5: Configure RPI and click “Finish >>”



Notes: We didn't configure the Vendor ID, Device Type, and Product Type because some Scanners do not require this information. But other Scanners do require this information.

The FC6A information can be found on page 451 of the manual.

■ Instance Attributes (Instance ID: 1)

ID	Access	Name	Data Type	Description	Attribute Value
1	Get	Vendor ID	UINT	Vendor identification number	159
2	Get	Device Type	UINT	General device type	14 (Programmable Logic Controller)
3	Get	Product Code	UINT	Product identification code	2000